

#### Applications of Machine Learning and Computer Vision in Analysis of Timepix3 Data

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## On the menu today



Several *selected* nice examples ... by no means exhaustive!

Topics:

- Trajectory estimation & reconstruction (CV),
- Particle identification (ML),

If interested, watch for references in the bottom of slides.

# Trajectory estimation



- Why?
  - To determine where ionizing particles come from.
  - To separate particles in complex interactions.
- How?
  - Particles with sufficient energy produce linear tracks.
  - Assuming 1 particle per track, we fit a line with least squares.
  - Are we done? 🙂
  - No, because of ... random noise, overlaps,  $\delta$ -rays, etc.
  - Solution: robust fitting!

## Robust trajectory estimation



- 1. Sample lines from the data at random.
  - 2. For each line, count hits closer than a threshold.
- 3. Remember the line with the most hits.
- Advantages:
  - Fast, easy to implement & generalize,
  - Estimates P(incorrect sampling),
  - Copes with  $\leq 50\%$  outliers.
- Improvement: weighting by energy.





#### Example: RANSAC in 3D



Considered model Best model so far Outliers 0 Inliers E (keV) 2000 -80 1750 -60 1500 1250. 9 600 V -40 1000 750F20 25005002000 250LO 1500I tel (HITI) 1000  $\begin{smallmatrix} 1600 & 1400 & 1200 & 1000 & 800 & 600 & 400 & 200 & 0 \\ 1600 & 1400 & 1200 & 1000 & 800 & 600 & 400 & 200 & 0 \\ \end{smallmatrix}$ 500 0 yrei (µm)

Inliers: 5 (current), 5 (best so far)

Bergmann et al.: *3D reconstruction of particle tracks in a 2 mm thick CdTe hybrid pixel detector*, EPJC 79/2, pp. 165

Mánek et al.: *Randomized Computer Vision Approaches for Pattern Recognition in Timepix and Timepix3 Detectors*, arXiv:1911.02367





#### Hough accumulator (1 of 204 hits processed)





Hough accumulator (1 of 204 hits processed)













Hough accumulator (1 of 204 hits processed)





#### Example: Hough in 3D



![](_page_11_Picture_2.jpeg)

![](_page_11_Figure_3.jpeg)

Mánek et al.: *Randomized Computer Vision Approaches for Pattern Recognition in Timepix and Timepix3 Detectors*, arXiv:1911.02367

# **Example: MoEDAL directions**

![](_page_12_Picture_1.jpeg)

![](_page_12_Picture_2.jpeg)

![](_page_12_Figure_3.jpeg)

## Particle identification – why?

![](_page_13_Picture_1.jpeg)

- Why?
  - To characterize unknown radiation fields.
  - To recognize (& compare) sources with known decay products.
- How? *Machine learning!* 
  - We pre-process tracks into feature vectors (e.g. E, shape, complexity).
  - Or just train a neural net from a 2-channel image!

#### Ion classification

 Ions of different elements deposit energy at various rates (dE/dx). Pixel Number Y [px

50

30

20

δ-rays

- Procedure:
  - 1. Find & separate ion core.
  - 2. Sample energy along its path.

![](_page_14_Figure_5.jpeg)

Core

![](_page_14_Picture_6.jpeg)

Energy [keV

10<sup>2</sup>

10

#### Ion classification

- Ions of different elements deposit energy at various rates (dE/dx).
- Procedure:
  - 1. Find & separate ion core.
  - 2. Sample energy along its path.
- Learning:
  - Annotated ~1K tracks of 5 species.
  - Trained k-NN classifier (k = 7).
  - 89.3% accuracy.

![](_page_15_Figure_9.jpeg)

![](_page_15_Figure_10.jpeg)

Mánek: Machine learning approach to ionizing particle recognition using hybrid active pixel detectors, FEE CTU Master's thesis, 2018

![](_page_16_Picture_0.jpeg)

# Ion classification (with rejection)

- Ions of different elements deposit energy at various rates (dE/dx).
- Procedure:
  - 1. Find & separate ion core.
  - 2. Sample energy along its path.
- Learning:
  - Annotated ~1K tracks of 5 species.
  - Trained k-NN classifier (k = 7).
  - New: reject if confidence < 90%.
  - 93.5% accuracy, ~25% rejected.

![](_page_16_Figure_11.jpeg)

Mánek: Machine learning approach to ionizing particle recognition using hybrid active pixel detectors, FEE CTU Master's thesis, 2018

## Ion momentum classification

![](_page_17_Picture_1.jpeg)

• Tracks at different energy levels have characteristic shapes (e.g. halo).

![](_page_17_Figure_3.jpeg)

- Procedure:
  - 1. Normalize tracks (in E, direction).
  - 2. Train a multi-layer perceptron (1×128) on pixel image (2×32×32).
- 87.7% accuracy.

![](_page_17_Figure_8.jpeg)

0.0

1.0

-0.8

-0.6

-0.4

-0.2

## Conclusion

![](_page_18_Picture_1.jpeg)

- Timepix3 energy and time-of-arrival response encodes incident particle information in complex manner.
- Classifier models can be successfully trained for inference of particle properties.
- Robust computer vision methods are viable and tractable means of pre-processing Timepix3 data in 2D and 3D.
- Many avenues still remain to be explored!

![](_page_19_Picture_0.jpeg)

#### Thank you for listening!

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![](_page_19_Picture_4.jpeg)